EECS205000: Linear Algebra College of Electrical Engineering and Computer Science National Tsing Hua University Spring 2019

Homework #2 Coverage: Chapter 1–5 Due date: 3 May, 2019

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## Notice:

- 1. Please hand in your answer sheets by yourself to TAs in the class time or to the WCSP Lab., EECS building, R706, before 23:59 of the due date. No late homework will be accepted.
- 2. This homework includes 9 problems with 100 points plus 5 bonus points.
- 3. Please justify your answers with clear, logical and solid reasoning or proofs.
- 4. You need to **print** the problem set and answer the problems in the **blank boxes** after each problem or sub-problm. We provided enough space for every problem. However, if you need more space, you can print it in one-side manner (each page in one side of an A4), and use the back side as an additional space.
- 5. Please do the homework independently by yourself. However, you may discuss with someone else but copyied homework is not allowed. This will show your respect toward the academic integrity.
- 6. Write your name, student ID, email and department on the begining of your ansewr sheets.
- 7. Your legible handwriting is fine. However, you are very welcome to use text formatting packages for writing your answers.

Name	
Student ID	
Department	
Email Address	

Problem	Score
1	
2	
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10	
Total	

**Problem 2.** (5 points) Let  $\mathbf{b}_1 = [1, 2, 2, 4]^T$ ,  $\mathbf{b}_2 = [-2, 0, -4, 0]^T$ , and  $\mathbf{b}_3 = [-1, 1, 2, 0]^T$ , and let S be the span of these vectors. Apply the Gram-Schmidt process to  $\{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$  to obtain an orthonormal basis  $\{\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3\}$  for S.

## **Problem 3. (20 points)** Let A be an $m \times n$ matrix.

- (a) (5 points) Show that  $N(\mathbf{A}^T \mathbf{A}) = N(\mathbf{A})$ .
- (b) (5 points) Show that  $rank(\mathbf{A}^T \mathbf{A}) = rank(\mathbf{A})$ . (Hint: you may use the rank-nullity theorem, i.e.  $dim(N(\mathbf{A})) + rank(\mathbf{A}) = n$  for any  $m \times n$  matrix  $\mathbf{A}$ .)
- (c) (10 points) If  $\mathbf{A}$  is a 4 × 3 matrix and  $\mathbf{A} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$ . Let  $\tilde{\mathbf{x}}$  be a least-squares solution that minimizes

 $\|\mathbf{b} - \mathbf{A}\mathbf{x}\|^2$  for  $\mathbf{b} = [0, 2, 1, -1]^T$ . Find  $\mathbf{p} = \mathbf{A}\tilde{\mathbf{x}}$  and give its physical meaning.

**Problem 4. (10 points)** Assume that the matrix set **M** consists of  $2 \times 2$  real matrices to form a vector space over  $\mathbb{R}^{2 \times 2}$ .

- (a) (5 points) Show that the subspace W consisting of symmetric matrices is a subspace of  $\mathbf{M}$ .
- (b) (5 points) Find a basis for W and determine the dimension of W.

**Problem 6.** (10 points) Let  $y = r + sx^2$ , where  $r, s \in \mathbb{R}$ , provide the least squares fit to the points  $(x_1, y_1) = (1, 1), (x_2, y_2) = (2, 4)$  and  $(x_3, y_3) = (4, 8)$ .

- (a) (5 points) Find r and s.
- (b) (5 points) Find values of  $y_1$ ,  $y_2$  and  $y_3$  at  $x_1 = 1$ ,  $x_2 = 2$  and  $x_3 = 4$ , respectively, such that the best fitting curve is y = 0.

**Problem 7.** (20 points) Let  $\mathbf{A} \in \mathbb{R}^{3 \times 5}$ . Assume that we performed row operations on  $\mathbf{A}$  to convert it to *rref* form, but now we do something different - instead of getting the usual  $\mathbf{R} = [\mathbf{I} \quad \mathbf{F}]$ , we now reduce it to a matrix in the form of  $\tilde{\mathbf{A}} = [\mathbf{F} \quad \mathbf{I}]$ . And the row operation of  $\mathbf{A}$  was given as follows:

$$\mathbf{A} \xrightarrow{rref} \begin{bmatrix} 2 & 3 & 1 & 0 & 0 \\ 4 & 5 & 0 & 1 & 0 \\ 6 & 7 & 0 & 0 & 1 \end{bmatrix} = \tilde{\mathbf{A}}$$

- (a) (10 points) Find a basis for  $N(\mathbf{A})$ .
- (b) (10 points) Find a matrix  $\mathbf{M}$  so that applying the same row elimination matrix associated with  $\tilde{\mathbf{A}}$  to  $\mathbf{A}\mathbf{M}$  can get the usual *rref* form.

$$\mathbf{AM} \xrightarrow{rref} \begin{bmatrix} 1 & 0 & 0 & 2 & 3 \\ 0 & 1 & 0 & 4 & 5 \\ 0 & 0 & 1 & 6 & 7 \end{bmatrix}$$

Problem 8. (10 points) Answer the following questions.

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(a) (5 points) Let 
$$\mathbf{A} = \begin{bmatrix} 1 & x & x^2 \\ 1 & y & y^2 \\ 1 & z & z^2 \end{bmatrix}$$
. Find  $det(\mathbf{A})$  in terms of  $x, y, z$ .

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(b) (5 points) Let matrix  $\mathbf{A} = [\mathbf{a}_1 \quad \mathbf{a}_2 \quad \mathbf{a}_3]$ , where  $\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3$  are vectors in  $\mathbb{R}^3$ . If  $4\mathbf{a}_1 - 3\mathbf{a}_2 + 2\mathbf{a}_3 = \mathbf{0}$ , find  $det(\mathbf{A})$ .

**Problem 9.** (10 points) Let C be the cofactor matrix of A, and  $\mathbf{C}^T = \begin{bmatrix} 2 & 1 & 0 \\ 4 & 3 & 2 \\ -2 & -1 & 2 \end{bmatrix}$ . Find the  $det(\mathbf{A})$  and A. (Hint: you may use  $det(c\mathbf{A}) = c^n det(\mathbf{A})$ ) for any constant c and  $n \times n$  matrix  $\mathbf{A}$ ).

**Problem 10.** (+5 bonus points) For maximizing your knowledge on Linear Algebra, please provide comments and suggestions of how to improve the teaching quality of this course.